



Quick Installation Guide (Local License): QUARCTM on Microsoft[®] Windows[®]

STEP 1 Install MATLAB® and Required Add-Ons

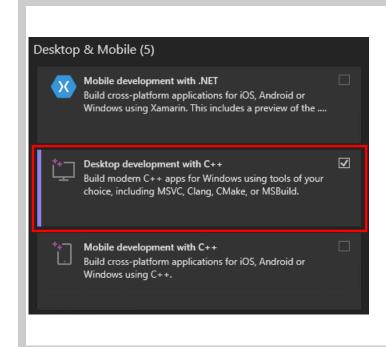
QUARCTM supports 64-bit Microsoft® Windows®.

Ensure one of <u>supported MATLAB</u> versions is installed on the computer with the following required add-ons accompanying the corresponding MATLAB version:

- Simulink®
- Simulink Coder™
- MATLAB Coder™ (required by Simulink Coder)
- Control System Toolbox™ (Optional add-on, but highly recommended as used by most of Quanser's control laboratories)

STEP 2 Install Microsoft Compiler

QUARC requires a MATLAB-supported C/C++ compiler



Depending on the MATLAB version used, ensure one of the following Microsoft compilers is installed:

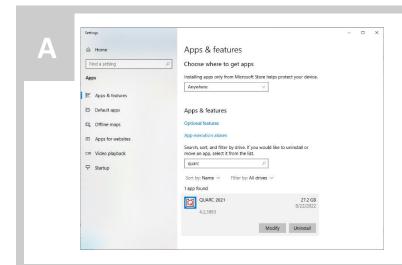
- Microsoft Visual Studio[®] 2019, or 2022 Professional Edition
- Microsoft Visual Studio 2019, or 2022 Community Edition

The Microsoft Visual Studio 2022 Community Edition can be installed using the following Microsoft-provided link (you will need to sign-in using a Microsoft account in order to download older versions of Visual Studio):

visualstudio.microsoft.com/downloads/

Ensure that the "Desktop development with C++" workload under "Desktop & Mobile" or "Windows" groupings is checked.

For details, refer to the online Compatibility Chart.



Uninstall any previous version of QUARC that may be present on the computer. Furthermore, if you have the QUBE-SERVO-USB, Q2-USB, or Q8-USB devices, you need to unplug them from the computer before uninstalling the earlier versions of QUARC.

Do so by launching the *Programs and Features* dialog or the *Apps & features* dialog depending on which Windows version you have.

B



- An internet connection is required during the QUARC installation process. Download the QUARC web installer executable using the link provided in the confirmation email that you received.
- Run the QUARC installer (i.e. install_quarc.exe). The QUARC installation screen should appear.

The installer automatically checks if there is a newer update ready to download.

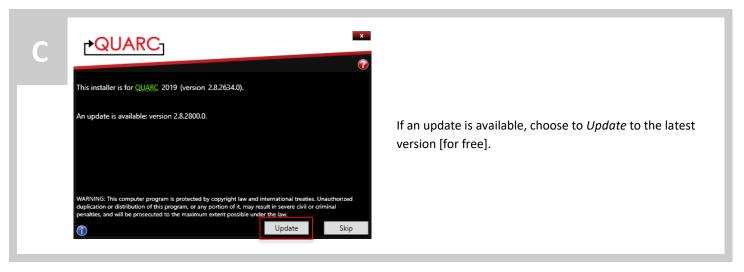
Tip: To find tips for each installation window, hover the mouse cursor

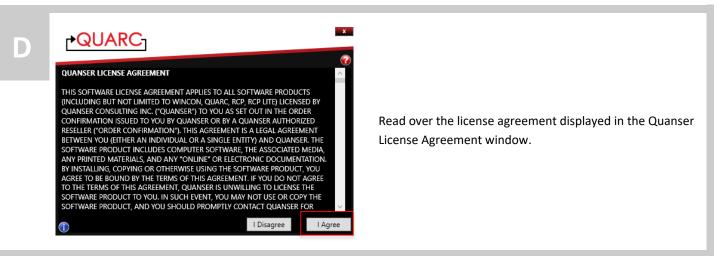


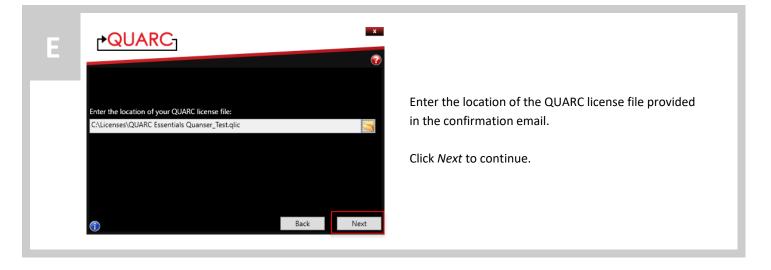
on the blue information icon on the lower left corner or



click the question mark icon on the upper right corner for more details from the installation guide.







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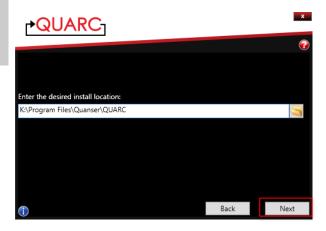


The installer will automatically scan the software environment on the computer to ensure it meets the requirements for QUARC. Please consult with the *QUARC Compatibility Table* by clicking the link on the installation window for details.

Start the installation with default settings by clicking *Install* and skip to Step I.

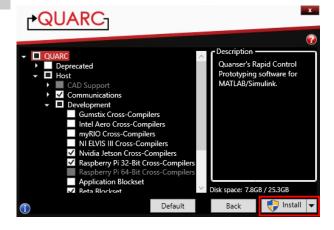
For more granular control of the installation process, click *Options*, and go to next step.

G



Provide the destination folder where QUARC will be installed and click *Next* to continue.

Н



Choose the features to be installed. If you don't have the proper license required for a feature, the feature will be disabled and greyed out.

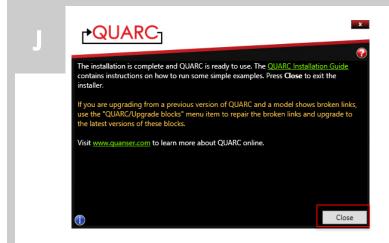
If you are using one of the devices below, please ensure the corresponding feature(s) is selected:

Device(s)	Feature(s)
Quanser QCar,	Nyidia latsan 7.4 Crass Campilors
QDrone2	Nvidia Jetson 7.4 Cross-Compilers
Quanser QBot	Nvidia Jetson 9.4 Cross-Compilers
Platform, QCar2	
Quanser QDrone	Intel Aero Cross-Compilers
Quanser QBot2e,	Raspberry Pi 32-Bit Cross-
QBot3	Compilers
Quanser QBot2,	
QBall 2+, QBall 2,	Gumstix Cross-Compilers, Beta
QBot, QBall-X4,	Blockset
HiQ	

Click Install and go to the next step.



A progress bar and embedded video should appear on the installation screen.

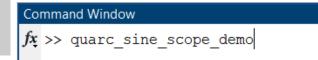


Once the installation is complete, click *Close* to finish the installation.

STEP 4 Software-only Test

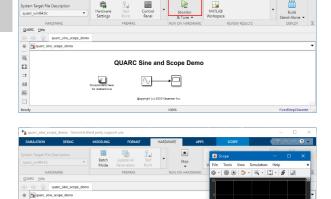
The QUARC Sine and Scope Demo used in this section is to confirm that QUARC has been installed properly.

A

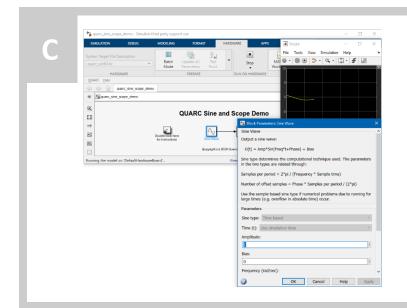


- In the MATLAB Command Window type quarc_sine_scope_demo, and press Enter.
- The **QUARC Sine and Scope Demo** Simulink model will open.

B



- Click on the Monitor & Tune button on the Hardware tab of the Simulink Toolstrip.
- Double-click on the **Scope** block.
- A sine wave of amplitude 1 should be plotted in realtime.



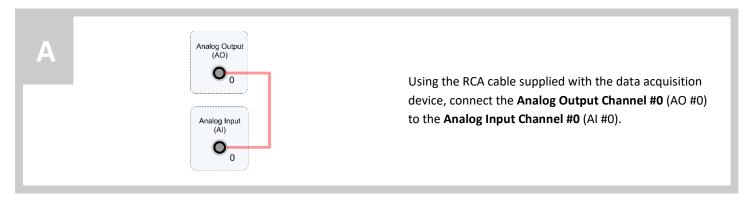
- Double-click on the Sine Wave block.
- Change the Amplitude to 5, then press the Apply button.
- The sine wave's amplitude would be changed to 5 in real-time.
- Change the Frequency (rad/sec) to 2, then press the Apply button
- The sine wave's frequency would be doubled in realtime



Click on the **Stop** button on the Hardware tab of the Simulink Toolstrip to stop the running model.

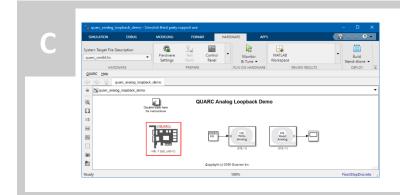
STEP 5 DAQ Test

The QUARC Analog Loopback Demo used in this section is to confirm QUARC has been installed properly. It also tests the data acquisition (DAQ) device on Windows.

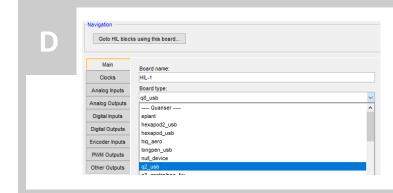


| Command Window | fx >> quarc_analog_loopback_demo

- In the MATLAB Command Window type quarc_analog_loopback_demo, and press Enter.
- The QUARC Analog Loopback Demo Simulink model will open.



Double-click on the QUARC HIL Initialize block.



- In the Board type option list under the Main tab, select the data acquisition device that is installed on the computer (e.g. q2_usb).
- Click on the **OK** button to close the *HIL Initialize* dialog.

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- Click on the **Monitor & Tune** button on the Hardware tab of the Simulink Toolstrip.
- Double-click on the **Scope** block.

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A 1-Hz half-wave rectified sine wave of amplitude 1 should be plotted in real-time. If not, go to the *Troubleshooting* section.

In the model, the Simulink Signal Generator block applies a 1-Hz sine wave signal of a 1-Volt amplitude to the selected DAQ analog output channel #0. Due to the RCA-cable connection, this signal is then acquired and read through the DAQ analog input channel #0.

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- Double-click on the **Signal Generator** block.
- Change the **Amplitude** to 2, then press the **Apply** button.
- The sine wave's amplitude would be changed to 2 in real-time.
- Change the Frequency to 2, then press the Apply button
- The sine wave's frequency would be doubled in realtime





Click on the **Stop** button on the Hardware tab of the Simulink Toolstrip to stop the running model.

Getting an 'Error configuring license' message from the Licensing Registration tool.

- Open the provided QUARC license file with Microsoft WordPad.
- Ensure your QUARC version is included within the range indicated by the license file *Minimum version*: and *Maximum version*: fields.
- Close Microsoft WordPad.
- Browse to the Quanser QUARC yyyy from Windows Start Menu (where yyyy is the version of QUARC that you have installed) and run the License Registration tool using a valid QUARC license file.
- For additional insights, run the Quanser License Viewer.

Getting error: 'Error occurred while executing External Mode MEX- file 'quarc_comm': An operating system specific kernel-level... driver for the specified card could not be found. The card or driver may not be installed...' when running a model

- If using a USB device, ensure the USB cable is properly connected, and try a different USB port on the computer.
- Verify the data acquisition (DAQ) device is properly connected to the computer.
- If this is a National Instruments (NI) data acquisition device, ensure the NI DAQmx drivers are installed. The NI DAQmx installer is on a DVD that comes with the NI hardware; it can also be downloaded from https://www.ni.com/drivers/

When running the DAQ Test, the Scope does not display a sine wave.

- Ensure the RCA loopback connection is made on the data acquisition (DAQ) device, as described in Step 5A.
- Verify that the proper DAQ device name was selected in the HIL Initialize dialog, as described in Step 5D.

Getting error: '??? Model ... failed to download to target 'shmem://quarc-target:1'. The code being downloaded or run is not compatible with the type of target referenced by... the target URI. For example, 32-bit code cannot be downloaded to a 64-bit target or vice-versa. In Simulink, make sure the system target file selected in the model's active configuration is compatible with the target referred to by the target URI.' when building a model

- Select the QUARC/Options... menu item from the Simulink model.
- Under *Code Generation*, click on the **Browse...** button.
- Select the system target file corresponding to your target computer (e.g. QUARC Win64 Target).
- Click on the OK buttons to close the dialogs, and save the model.

Getting an error when trying to build the QUARC Sine and Scope Demo

- Type **ver** in the MATLAB Command Window.
- QUARC should appear in the displayed list.
- Depending on the compiler used, refer to Section 3 of the QUARC Installation Guide, and review your compiler installation steps.
- Run mex –setup in the MATLAB Command Window, as described in the QUARC Installation Guide.

The QUARC license file has been registered successfully, but you get an 'Error configuring license' message when trying to run a QUARC model.

- If you just reconfigure the license using the License Registration tool, please make sure to restart MATLAB for the license changes to take effect.
- Run the QUARC Sine and Scope Demo, as described in Step 4.
- If the QUARC Sine and Scope Demo runs as expected, then your QUARC license file
 does not allow some of the features used by your QUARC model. Contact
 Quanser's technical support for further information.
- Otherwise and if the same error message remains, first disable any antivirus software and Windows Firewall. Then browse to the *Quanser QUARC yyyy* from Windows Start Menu (where yyyy is the version of QUARC that you have installed) and run the *License Registration* tool, using a valid QUARC license file.

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