

QLabs Hybrid System Configuration Guide

This document outlines the steps required to configure your system to run both Quanser hardware with <u>QUARC</u> for MATLAB Simulink and QLabs Virtual Experiments. Configuration changes to convert Simulink models from Quanser hardware resources to work with QLabs Virtual Experiments are also included.

STEP 1 Install QUARC

 Follow the QUARC Quick Installation Guide to install QUARC 2025. Ensure one of <u>supported MATLAB</u> versions is installed on the computer. Quanser Interactive Labs should be installed as part of the QUARC installation procedure, if supported by your QUARC license. Be sure to reach out to the Quanser team to confirm that your license supports QLabs. We recommend that you uncheck any optional cross-compilers that are not needed to save disk space and installation time.

When using the full QUARC Real-Time Control Software with Quanser Interactive Labs, the Simulink models for QLabs Virtual Experiments need to be configured in *External* mode and used to build/generate code, similarly as is done when using the hardware. In the standard QLabs Virtual Experiments configuration, the Simulink models supplied with the virtual courseware are configured to *Normal* mode for standard simulation (i.e., no code generation). When using the Hybrid Configuration, use the Quanser hardware courseware models from www.quanser.com/resources and perform the following modifications for use with the virtual system:

STEP 2 Open Model

- 1. Download the Simulink models for your Quanser virtual system from <u>www.quanser.com/resources</u>. These are the models that have been configured for the hardware and need to be converted to use with QLabs.
- 2. Open the Simulink model to configure in MATLAB Simulink.

STEP 3 Configure HIL Initialize Block

1. Locate and open the **HIL Initialize** block in the model. As shown in Figure 1, go to the **Main** pane and ensure the **Board type** corresponds to your product is selected, as listed in Table 1.

Note: If you are using a Q2-USB or an older DAQ board such as a Q8, set the board type to **Q8-USB** instead.

2. Append the **Board identifier** field as follows:

O@tcpip://localhost:XXXXX

where **XXXXX** refers to the HIL port number provided in Table 1.

3. Click the **OK** button to accept the applied changes.

HIL Initialize			
Initializes a hardw	vare-in-the-loop card.		
Navigation			
Goto HIL block	s using this board		
Main	Board name:		
Clocks	HL-1		
Analog Inputs	Board type:		
Analog Outputs	qube_servo2_usb		~
	Board identifier:		_
Digital Inputs	0@tcpip://localhost:18920		
Digital Outputs	Board-specific options:		
Encoder Inputs			
PWM Outputs	Assume exclusive access to the board		
Other Outputs			
	QUBE Servo 2.0 USB		
	_		
	and the second		
	Q GUANSER monorate standard		

Figure 1: Example of a HIL Initialize block configured for a QUBE-Servo 2

Virtual Product	HIL Board type	HIL Port Number	
QUBE-Servo 2 with Disc	qube_servo2_usb	18920	
QUBE-Servo 2 with Pendulum	qube_servo2_usb	18921	
QUBE Servo 3 with Disc	qube_servo3_usb	18922	
QUBE Servo 3 with Pendulum	qube_servo3_usb	18923	
Aero	quanser_aero_usb	18930	
Aero 2	quanser_aero2_usb	18950	
QArm	quanser_qarm_usb	18900	
QBot 2e	qbot2e	18910	
QBot 3	qbot3	18910	
QBot Platform	qbot_platform	18914	
Coupled Tanks	q8_usb	18950	
Rotary Servo (SRV02)	q8_usb	18940	
Flexible Link (SRV02)	q8_usb	18941	
Ball and Beam (SRV02)	q8_usb	18942	
Pendulum (SRV02)	q8_usb	18943	
QCar	qcar	18960	
QCar 2	qcar2	18960	
QDrone 2	qdrone2	18981	

Table 1: List of HIL port numbers for Quanser virtual plants

STEP 4 Configure Video3D Initialize Block

1. If your model uses Video3D blocks, open the **Video3D Initialize** block as shown in Figure 4, and modify the **Device identifier** field as follows:

0 @ t	tcpip://	localhost:XXXXX	Δ			
where XXXXX refers to the Video3D port n	umber pr	ovided in Table 2.				
皆 Block Parameters:	Video3D Initialize	×				
– Video3D Initialize (n	nask) (link)					
Initializes a 3D imag	je sensor.					
Navigation						
Go to	Video3D blocks	using this device				
Parameters						
Video device name:						
Video3D-1	Video3D-1					
Source of data: De	Source of data: Device 🔹					
Device identifier:						
0@tcpip://localhost:18911						
Sample time (seconds):						
qc_get_step_size * ceil(0.033 / qc_get_step_size)						
Active during nor	mal simulation					
	OK Can					
Figure 4: Configuring t	he Video3i	D Initialize block for (a QBot 2e			
Table at list of Videoop) nort nun	bara far Ougnaar uir	tual plants			
Table 2: List of Video3D			lual plants			
Virtual Proc	luct	Video3D Port				
		Number				
QArm Cam	era	18901				

1. To test your model, open the QLabs application and select the Workspace of the appropriate virtual product.

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18986

- 2. Click on the **Monitor & Tune** button on the *HARDWARE* tab of the Simulink model (or use the QUARC tab).
- 3. If your model was configured correctly, it should run and display results similar to those provided in the Student and Instructor resources of your specific product.

Still Need Help? If you have any issues with running QLabs, please go to the <u>QLabs support page</u>. For further assistance from a Quanser engineer, contact us at <u>tech@quanser.com</u>

QBot 2e Camera

QBot 3 Camera

QBot Platform Camera

QCar Camera

QCar 2 Camera

QDrone 2 Camera

STEP 5 Test Your Model